Imagetext 1:

The fully autonomous test vehicle of the Chair for Sustainable Transport Logistics 4.0 at the Johannes Kepler University Linz on the test track in St. Valentin, Lower Austria

Imagetext 2:

In this study, LiDAR and cameras were tested to determine how well they were able to detect their environment, possible obstacles, and road markings, in particular.

*Photos: Lehrstuhl Nachhaltige Transport Logistik 4.0, Johannes Kepler Universität Linz, Digitrans (frei)*